

Bayesian inference and generative models in neuroscience

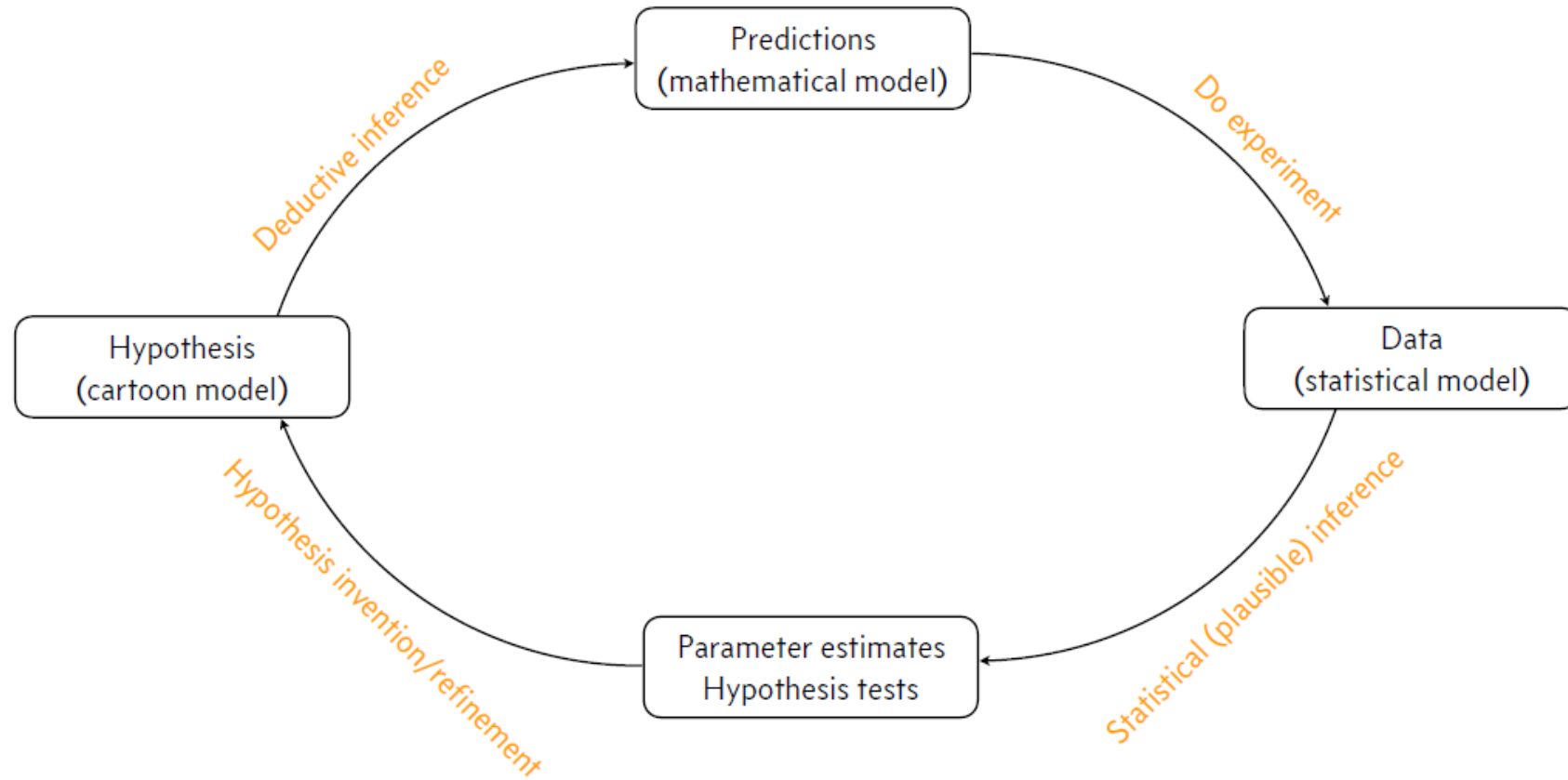
Nhat Le, Peer lecture 3/31/2019

What is the goal of doing (neuroscience) experiments?

Is it...

- To further knowledge?
- To test a hypothesis?
- To explore and observe?
- To demonstrate a method?
- To graduate?

The scientific process



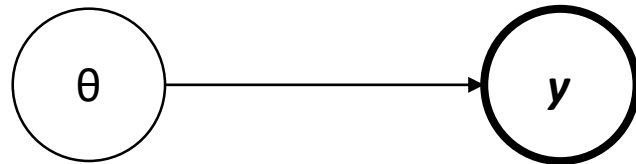
Frequentist vs Bayes

- ***Frequentist probability***: $P(A)$ represents long-run frequency over a large run of repetitions of the experiment.
- ***Bayesian probability***: $P(A)$ represents the degree of belief / plausibility about A

Generative (statistical) model

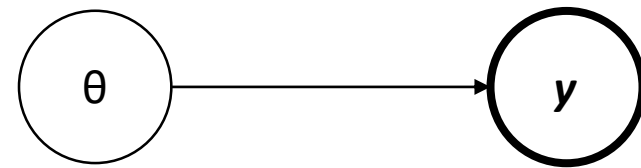
A generative model describes our beliefs about:

- The sources of error or uncertainty in the data
- Uncertainty in the underlying parameters of the model



Data is generated from hidden (latent) parameters

- ‘Data’: any observable measurements
 - Firing rate
 - Behavior
 - Protein levels
 - Sentences in a language
- ‘Hidden’ parameters govern the generation of data
 - Resting potential of neurons
 - Emotional state
 - Gene sequence
 - Grammar rules



Bayes rule

*Parameter
(not observed)* →

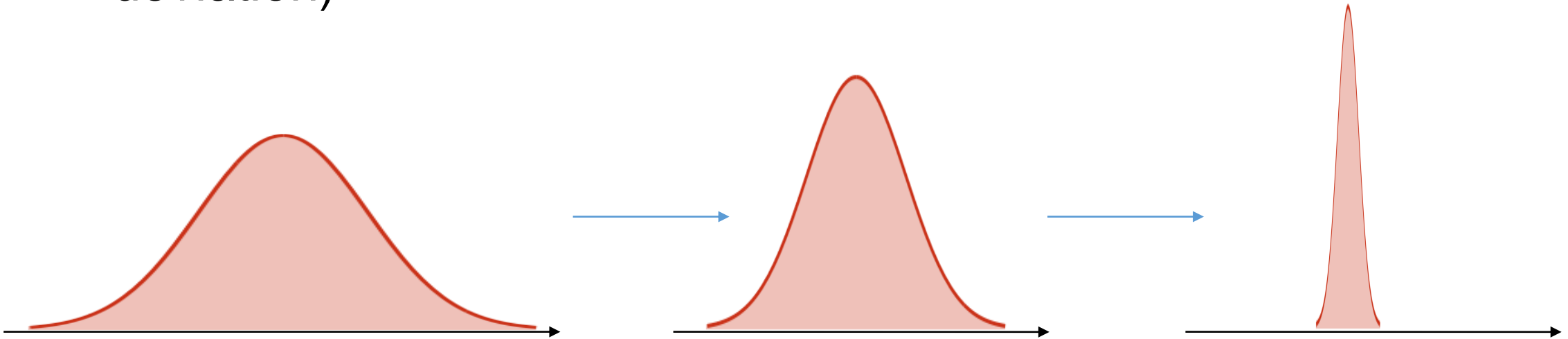
Data (observed) ↓

$$P(\theta | y) = \frac{P(y | \theta) P(\theta)}{P(y)}.$$

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}}.$$

Our job is to infer hidden parameters, given observed data

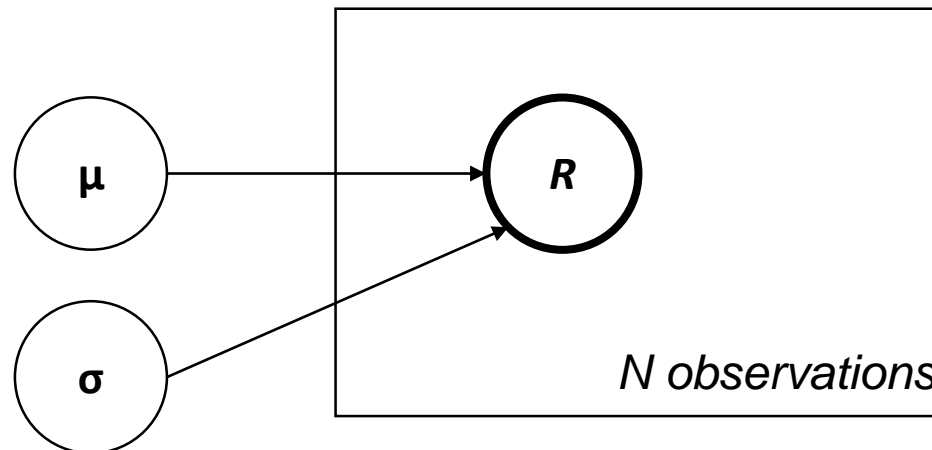
- Bayesian analysis is composed of three steps:
 1. Build a model, i.e. define a likelihood $p(D|\theta)$ and a prior $p(\theta)$
 2. Compute the posterior $p(\theta|D)$
 3. Report some summary of the posterior (mean and standard deviation)



An example: neuron firing rate

- Average firing rate R modelled as normally distributed
- **Parameters of the model:** mean μ and standard deviation σ
- **Observed data:** average firing rates R for different trials

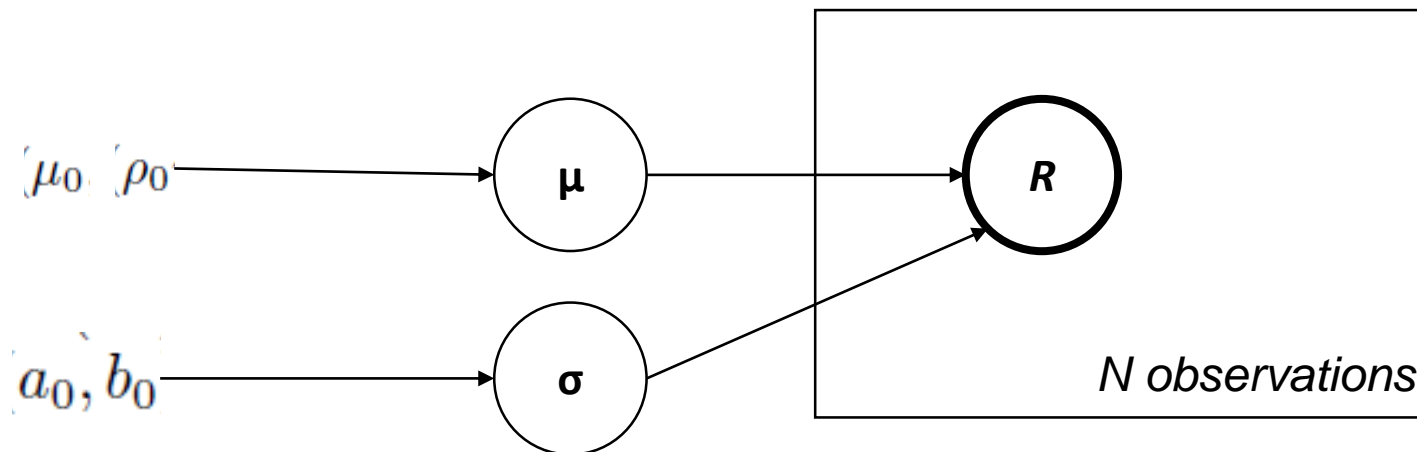
Inference objective: infer the likely values of μ and σ based on observed firing rates.



An example: neuron firing rate

- Average firing rate R modelled as normally distributed
- **Parameters of the model:** mean μ and standard deviation σ
- **Observed data:** average firing rates for different trials

Inference objective: infer the likely values of μ and σ based on observed firing rates.



$$y_n \stackrel{iid}{\sim} \mathcal{N}(\mu, \tau^{-1}), \text{ where } \tau = (\sigma^2)^{-1}$$

$$\tau \sim \text{Gamma}(a_0, b_0)$$

$$\mu \mid \tau \sim \mathcal{N}(\mu_0, (\rho_0 \tau)^{-1})$$

Exact Inference

- Evaluate the posterior directly using Bayes' rule
- Main challenge: compute the evidence (denominator)

$$P(\theta | y) = \frac{P(y | \theta) P(\theta)}{P(y)}.$$

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}}.$$

Conjugate priors

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}}$$

Posterior can be easily evaluated if likelihood and priors come from 'conjugate families'

Likelihood	Conjugate prior	Posterior update
$x \sim \text{Normal}(\mu=z, 1)$	$z \sim \text{Normal}(\mu_0, \sigma_0^2)$	$z x \sim \text{Normal}\left(\frac{x + \mu_0/\sigma_0^2}{1 + \sigma_0^2}, \frac{1}{1 + \sigma_0^2}\right)$
$x \sim \text{Normal}(\mu=0, \sigma^2=z)$	$z \sim \text{InvGamma}(\alpha, \beta)$	$z x \sim \text{InvGamma}(\alpha + 1/2, \beta + 1/2 x^2)$
$x \sim \text{Bernoulli}(p=z)$	$z \sim \text{Beta}(\alpha, \beta)$	$z x \sim \text{Beta}(\alpha + x, \beta + 1 - x)$

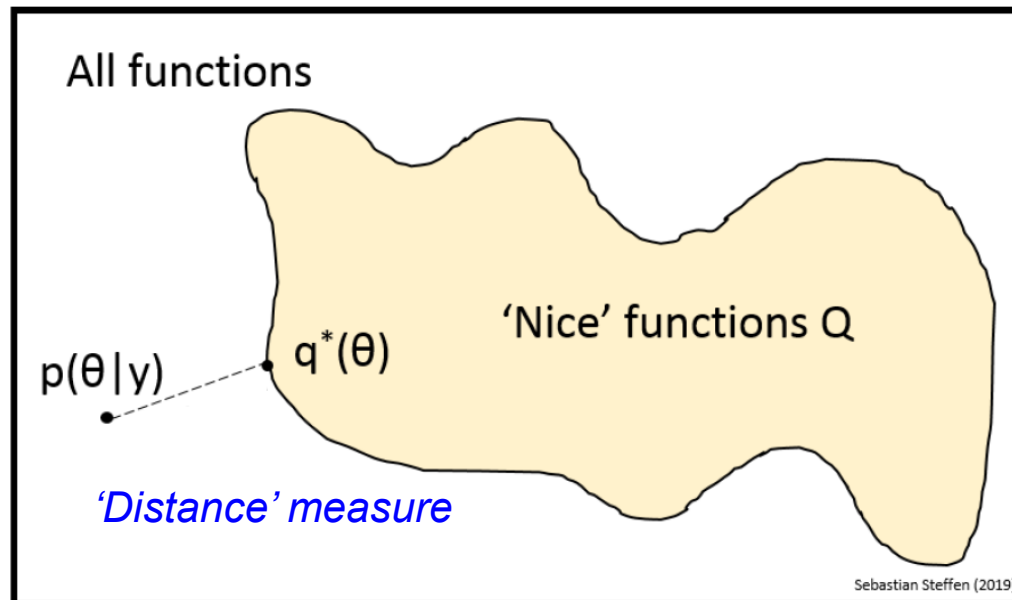
For a list of conjugate pairs: https://en.wikipedia.org/wiki/Conjugate_prior

Approximate inference

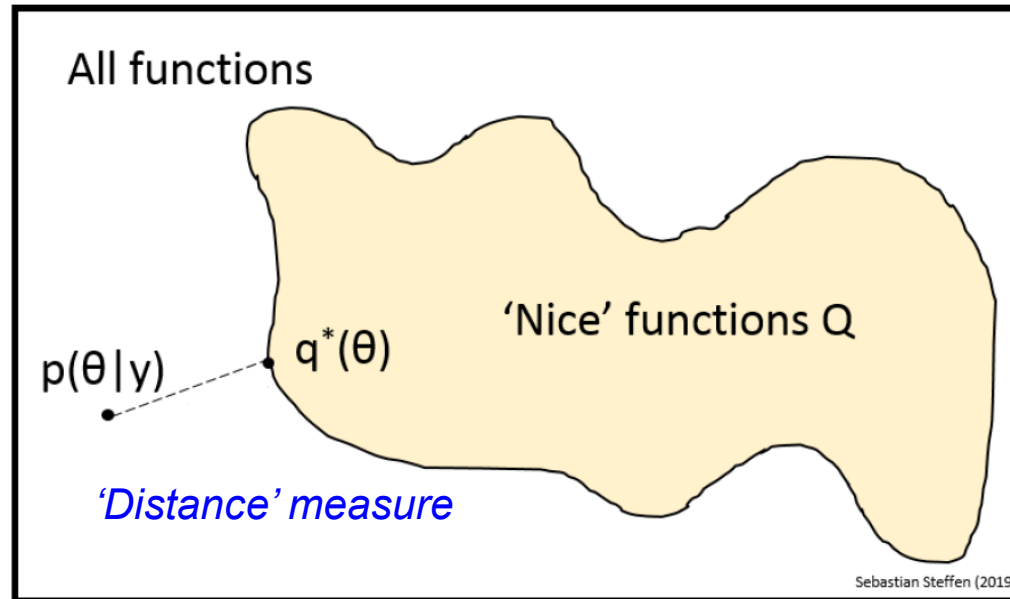
- Most of the time, exact inference is not possible
→ Have to resort to approximate inference
- Two ways of doing this
 - Approximate inference by optimization
 - Approximate inference by sampling

Approximate inference by optimization (aka Variational inference)

- Can't evaluate posterior $P(\theta | y)$ directly
- **Strategy:** approximate it with some distribution $q(\theta)$



Choices



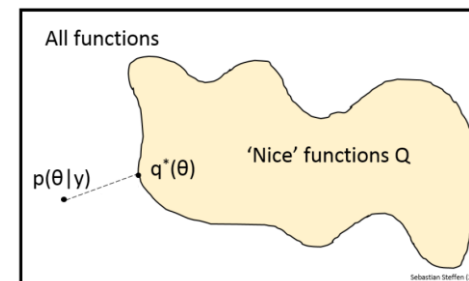
1. Choice of distance measure is KL-divergence
2. Choice of 'nice' functions is often the mean-field approximation
3. Choice of optimization procedure is coordinate ascent

Objective: minimize distance

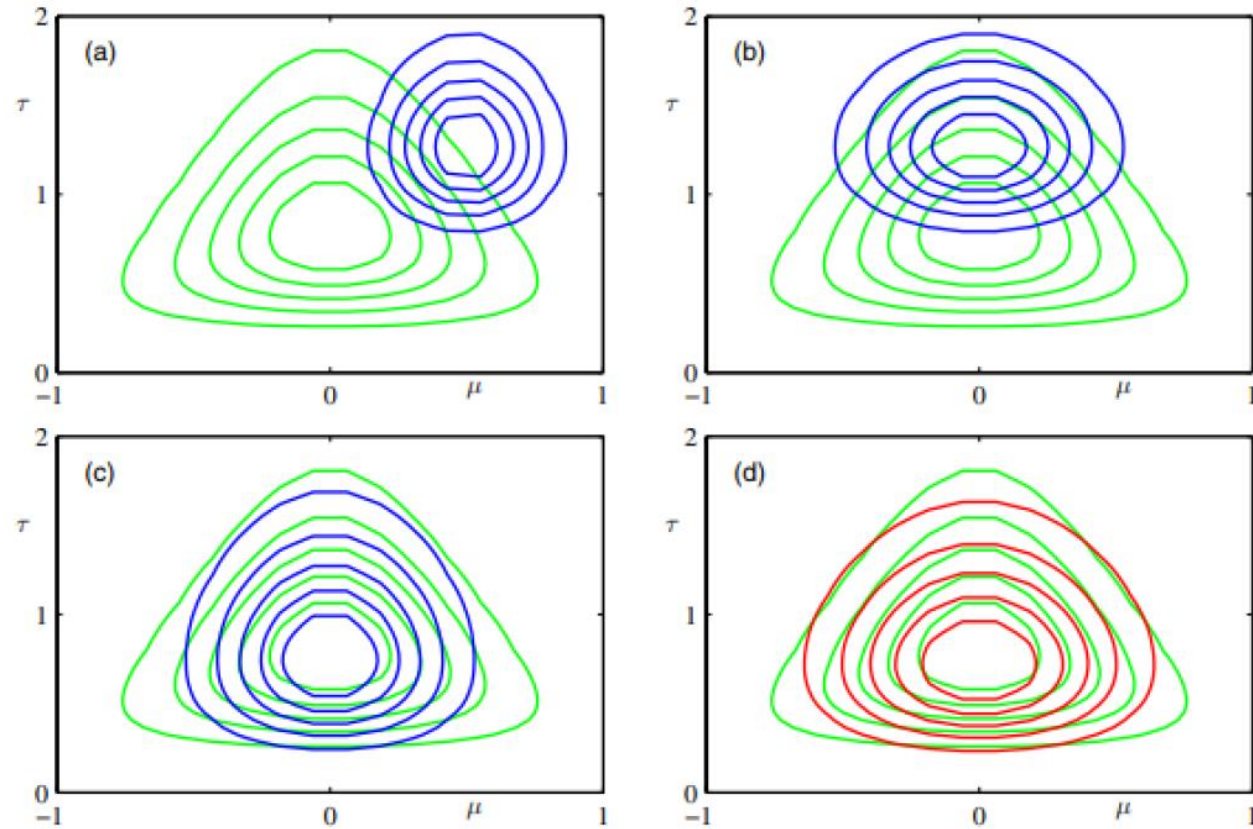
$$D_{\text{KL}}[Q(z) \parallel p(z|x)] = -E_{z \sim Q} \left[\log \frac{p(z|x)}{Q(z)} \right]$$

$$= -E_{z \sim Q} \left[\log p(z,x) - \log Q(z) \right] + \text{const.}$$

ELBO (evidence lower bound)
Lower bound on $\log p(x)$



To minimize distance, perform coordinate ascent



Free energy



- *Free energy is the ELBO!*

- Brief explanation:

$$P(\bar{o}, \bar{s}, \pi, a, b, d, \beta)$$

The world's generative model, a joint distribution over observations, outcome probabilities, state-related variables, and the agent's policies

$$Q(\bar{s}, \pi, a, b, d, \beta)$$

The agent's approximation of the generative model

Agent's objective: minimize $\text{KL}(P \parallel Q) \rightarrow$ maximize ELBO = minimize free energy

Approximate inference by sampling

- Can't evaluate posterior $P(\theta | y)$ directly
- **Strategy:** draw samples from the posterior

Markov Chain Monte Carlo (MCMC)



Stanisław Ulam

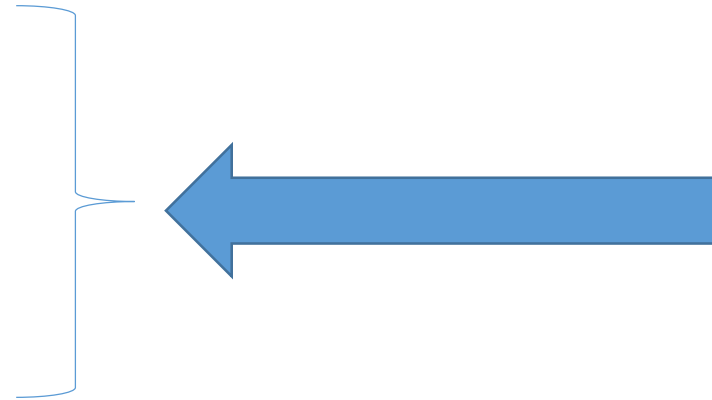
Monte Carlo inference

- We want to sample from some distribution
 - In this case, a posterior $p(z|x)$
- We can't sample from p directly, but maybe we can evaluate it
 - Or maybe we can only evaluate an unnormalised version of it, e.g. $p(z, x)$

Take samples from some other distribution (e.g. prior) and transform/reweight/etc. them so that they become samples from the posterior

Sampling techniques

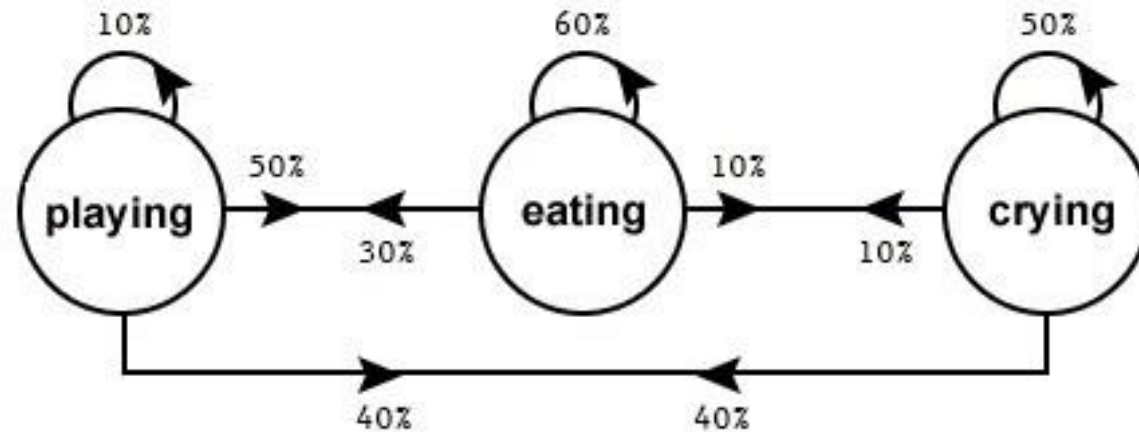
- Many different ways to sample
 - Importance sampling
 - Rejection sampling
 - MCMC (Markov Chain Monte Carlo)
 - Gibbs sampling
 - Slice sampling
 - HMC
 - NUTS



A Markov Chain

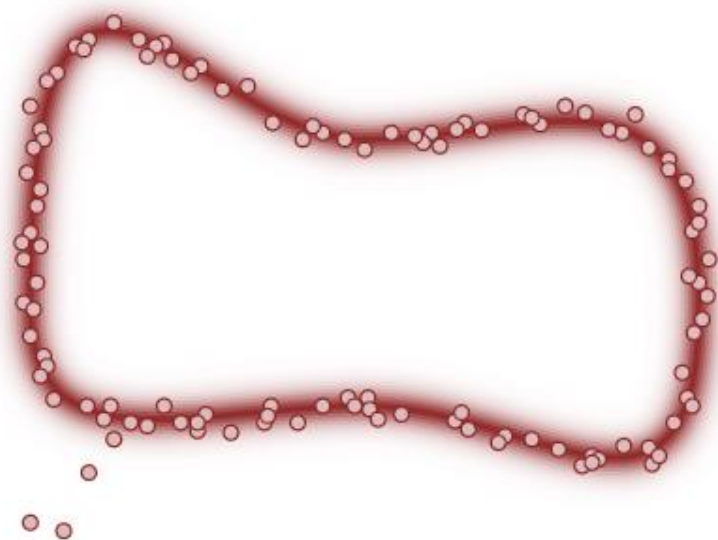
A random walk in which the next step depends only on where you are now

Markov state diagram of a child behaviour



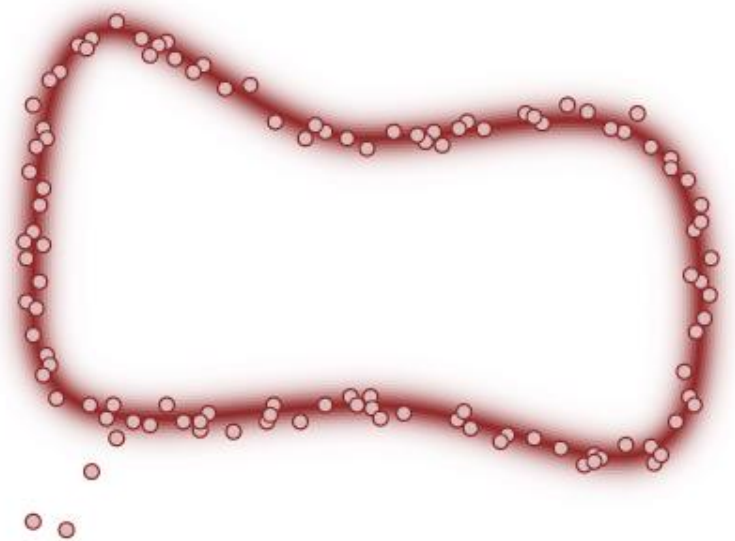
MCMC methods

- Idea: take random walks in the parameter space to sample from the target distribution



MCMC convergence

- To ensure that the final samples indeed come from the target distribution, we need to satisfy a few conditions
 - Detailed balance: eventually converges to the target distribution
 - Ergodicity: able to get to any point in parameter space in finite time



Some MCMC algorithms

1. Random-walk Metropolis-Hastings
 - Propose new candidate states, accept/reject the proposal with some probability
2. Gibbs sampling
 - For n parameters, fix $(n - 1)$ of them and sample from the conditional distribution
3. Hamiltonian Monte Carlo
 - Make use of extra momentum variables to flow through parameter space

Demo of MCMC in action

How can I get started with these inferences for my data analysis?

Stan will help you!

State-of-the-art platform for statistical modeling

Supports:

- Full Bayesian statistical inference with MCMC sampling (NUTS, HMC)
- Approximate Bayesian inference with variational inference (ADVI)

Interfaces with most popular data analysis languages (Python, MATLAB, R)



Simple syntax

```
data {  
  int<lower=0> N;           // number of neurons measured  
  real y[N];              // firing rates  
  
  // prior parameters  
  real mu_0;  
  real<lower=0> rho_0;  
  real<lower=0> alpha_0;  
  real<lower=0> beta_0;  
}
```

Simple syntax

```
parameters {  
  real mu;  
  real<lower=0> tau; //precision  
}  
  
model {  
  tau ~ gamma(alpha_0, beta_0);  
  mu ~ normal(mu_0, 1 / (rho_0 * tau));  
  for( n in 1:N )  
    y[n] ~ normal(mu, 1 / tau);  
}
```